## L-509 <br> Precision Linear Stage

## Compact Design, for Loads to 10 kg



- Travel ranges from 26 to 102 mm (1" to 4")
- Repeatability to $0.1 \mu \mathrm{~m}$
- Optional with Direct Measuring Linear Encoder
- Efficient ActiveDrive DC servo motor, Stepper Motor or DC Gear Motor
- Direction-sensing reference point switch
- Integrated optical limit switches


## Reference-class linear stage

High travel accuracy and load capacity due to crossed roller guides. Precision ball screw with 1 mm pitch. Compact design. Stress-relieved aluminum base for highest stability. Optical limit switches. Travel ranges of the variants: L-509.1: 26 mm (1'), L-509.2: 52 mm (2'), L-509.4: 102 mm (4").

## Drive types

- .xxAD variant: ActiveDrive DC motor for high velocity: Control via pulse-width-modulated (PWM) signals, the operating voltage is attained via an amplifier integrated in the motor housing.
- .xxDG variant: DC servo motor with gearhead for high torques and resolution at low motor power
- .xxSD variant: 2-phase stepper motor for low velocity and high resolution

Noncontact limit switches. Noncontact optical reference point switch with direction sensing in the middle of the travel range.

## Position measurement

- Integrated rotary encoder on the motor shaft (variants with DC gear motor).
- Laterally mounted linear encoder. Direct position measurement of the motion platform without influence on the positioning precision by mechanical play or hysteresis in the drivetrain

Min. incremental motion and slow motion
In conjunction with the SMC Hydra controller, versions with stepper motor and integrated linear encoder (L509.xASDOO) achieve repeatable minimum incremental motion in the range of the sensor resolution. The same configuration attains constant low velocities of a few sensor increments per second.

## Fields of application

Precision positioning in industry and research, high duty cycles.

## Specifications

|  | L-509.x4AD00 | L-509.x0AD10 | L-509.x0DG10 | L-509.xASD00 | L-509.x0SD00 | Unit | Tolerance |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Linear stage with ActiveDrive DC motor and linear encoder (direct position measurement) | Linear stage with ActiveDrive DC motor and rotary encoder | Linear stage with DC gear motor and rotary encoder | Linear stage with stepper motor and linear encoder (direct position measurement) | Linear stage with stepper motor |  |  |
| Motion and positioning |  |  |  |  |  |  |  |
| Travel range* | 26/52 / 102 | 26/52 / 102 | 26/52 / 102 | 26/52 / 102 | 26/52 / 102 | mm | max. |
| Integrated sensor | Linear encoder | Rotary encoder | Rotary encoder | Linear encoder | - |  |  |
| Sensor resolution rotary encoder | - | 16384 | 4096 | - | - | cts./rev. |  |
| Design resolution | 0.05 | 0.06 | 0.008 | 0.001** | 0.315*** | $\mu \mathrm{m}$ | typ. |
| Minimum incremental motion | 0.2 | 0.8 | 0.1 | 0.01 | 0.315*** | $\mu \mathrm{m}$ | typ. |
| Unidirectional repeatability | 0.1 | 0.2 | 0.1 | - | 0.3 | $\mu \mathrm{m}$ | typ. |
| Backlash | 0.2 | 0.3 | 1 |  | 0.5 | $\mu \mathrm{m}$ | typ. |
| Bidirectional repeatability | $\pm 0.3$ | $\pm 0.5$ |  | $\pm 0.2$ |  | $\mu \mathrm{m}$ |  |
| Crosstalk, angular error xry (pitch) | $\begin{aligned} & \pm 60 / \pm 90 / \\ & \pm 120 \end{aligned}$ | $\begin{aligned} & \pm 60 / \pm 90 / \\ & \pm 120 \end{aligned}$ | $\begin{aligned} & \pm 60 / \pm 90 / \\ & \pm 120 \end{aligned}$ | $\begin{aligned} & \pm 60 / \pm 90 / \\ & \pm 120 \end{aligned}$ | $\begin{aligned} & \pm 60 / \pm 90 / \\ & \pm 120 \end{aligned}$ | $\mu \mathrm{rad}$ | typ. |
| Crosstalk, angular error xrz (yaw) | $\begin{aligned} & \pm 60 / \pm 90 / \\ & \pm 120 \end{aligned}$ | $\begin{aligned} & \pm 60 / \pm 90 / \\ & \pm 120 \end{aligned}$ | $\begin{aligned} & \pm 60 / \pm 90 / \\ & \pm 120 \end{aligned}$ | $\begin{aligned} & \pm 60 / \pm 90 / \\ & \pm 120 \end{aligned}$ | $\begin{aligned} & \pm 60 / \pm 90 / \\ & \pm 120 \end{aligned}$ | $\mu \mathrm{rad}$ | typ. |
| Max. velocity | 50 | 50 | 3 | 20 | 20 | $\mathrm{mm} / \mathrm{s}$ | max. |
| Mechanical properties |  |  |  |  |  |  |  |
| Spindle pitch | 1 | 1 | 1 | 1 | 1 | mm |  |
| Gear ratio | - | - | 2401:81 | - | - |  |  |


| Load capacity | 100 | 100 | 100 | 100 | 100 | N | max. |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Push/pull force | 60 | 60 | 60 | 60 | 60 | N | max. |
| Permissible lateral force | 50 | 50 | 50 | 50 | 50 | N | max. |
| Holding force | 15 | 15 | 60 | 60 | 60 | $N$ | max. |
| Drive properties |  |  |  |  |  |  |  |
| Motor Type | DC motor with PWM control | DC motor with PWM control | DC gear motor | 2-phase stepper motor | 2-phase stepper motor |  |  |
| Operating voltage | 24 | 24 | 0 to $\pm 12$ | 24 | 24 | V |  |
| Motor power | 80 | 80 | 8.5 |  |  | W | nominal |
| Reference and limit switches | Optical | Optical | Optical | Optical | Optical |  |  |
| Miscellaneous |  |  |  |  |  |  |  |
| Operating temperature range | 0 to 55 | -20 to 65 | -20 to 65 | 0 to 55 | -20 to 65 | ${ }^{\circ} \mathrm{C}$ |  |
| Material | Aluminum, steel | Aluminum, steel | Aluminum, steel | Aluminum, steel | Aluminum, steel |  |  |
| Mass | 1.4 / 1.6 / 1.9 | 1.4 / 1.6 / 1.9 | 1.4 / 1.6 / 1.9 | 1.4 / 1.6 / 1.9 | 1.4 / 1.6 / 1.9 | kg |  |
| Connector | Sub-D 15 <br> (Motor and Encoder), 3 m cable incl. | Sub-D 15 <br> (Motor and Encoder), 3 m cable incl. | HD Sub-D 26 (motor and rotary encoder) to Sub-D 15, incl. 3 m cable | HD Sub-D 26 (motor), SubD 9 (linear encoder), 3 m cable set incl. | HD Sub-D 26 (motor) to Sub-D 15, 3 m cable incl. |  |  |
| Recommended controller/driver | $\begin{aligned} & \text { C-863 (single- } \\ & \text { axis) } \\ & \text { C-884 (up to } 4 \\ & \text { axes) } \end{aligned}$ | C-863 (singleaxis) <br> C-884 (up to 4 axes) | C-863 (singleaxis), C-884 (up to 4 axes) | SMC Hydra (double-axis) | C-663 (singleaxis) |  |  |

All cables required for operation with the recommended controller are included in the scope of delivery. Cables for connecting to other controllers can be ordered as accessory.

* Travel ranges of the variants: L-509.1: 26 mm (1"), L-509.2: 52 mm (2"), L-509.4: 102 mm (4").
** $\mathrm{Sin} / \mathrm{cos}$ analog signals with $1 \mathrm{~V}_{\mathrm{pp}}$, operation with SMC Hydra controller with maximum interpolation.
*** 200 full steps/rev., max. 1.2 A/phase. Motor resolution with C-663 stepper motor controller.
Ask about custom designs!


## Drawings and Images



L-509 versions with DC gear motor, dimensions in mm


|  | A | B | C | D | E |
| :---: | :---: | :---: | :---: | :---: | :---: |
| L-509.10SD00 | 129,3 | 100 | 135,3 | 78 | - |
| L-509.1ASD00 | 129,3 | 100 | 135,3 | 78 | 104,2 |
| L-509.20SD00 | 138,8 | 100 | 154,3 | 78 | - |
| L-509.2ASD00 | 138,8 | 100 | 154,3 | 78 | 104,2 |
| L-509.40SD00 | 163,8 | 150 | 204,3 | 78 | - |
| L-509.4ASD00 | 163,8 | 150 | 204,3 | 78 | 104,2 |

L-509 versions with stepper motor, dimensions in mm


|  | A | B | C | D | E |
| :---: | :---: | :---: | :---: | :---: | :---: |
| L-509.10AD10 | 157,3 | 100 | 135,3 | 106 | - |
| L-509.14AD00 | 157,3 | 100 | 135,3 | 106 | 104,2 |
| L-509.20AD10 | 166,8 | 100 | 154,3 | 106 | - |
| L-509.24AD00 | 166,8 | 100 | 154,3 | 106 | 104,2 |
| L-509.40AD10 | 191,8 | 150 | 204,3 | 106 | - |
| L-509.44AD00 | 191,8 | 150 | 204,3 | 106 | 104,2 |

L-509 versions with ActiveDrive DC motor, dimensions in mm


Detail drawing of the sled of the L-509

## PI



L-511 and L-509 precision stages can be combined without adapter plate for multi-axis positioning on several axes


Multi-axis set-up with L-511 (horizontal) and L-509 (vertical) precision stages


Direction of the axes and torques for linear stages

## Ordering Information

## L-509.10AD10

Precision Linear Stage, 85 mm Width, ActiveDrive DC Motor, 26 mm (1") Travel Range, Optical Limit Switches

## L-509.10DG10

Precision Linear Stage, 85 mm Width, DC Gear Motor, 26 mm (1") Travel Range, Optical Limit Switches L-509.10SD00
Precision Linear Stage, 85 mm Width, 2-Phase Stepper Motor, 26 mm (1") Travel Range, Optical Limit Switches

## L-509.20AD10

Precision Linear Stage, 85 mm Width, ActiveDrive DC Motor, 52 mm (2") Travel Range, Optical Limit Switches

## L-509.20DG10

Precision Linear Stage, 85 mm Width, DC Gear Motor, 52 mm (2") Travel Range, Optical Limit Switches L-509.20SD00
Precision Linear Stage, 85 mm Width, 2-Phase Stepper Motor, 52 mm (2") Travel Range, Optical Limit Switches

## L-509.40AD10

Precision Linear Stage, 85 mm Width, ActiveDrive DC Motor, 102 mm (4") Travel Range, Optical Limit Switches

## L-509.40DG10

Precision Linear Stage, 85 mm Width, DC Gear Motor, 102 mm (4") Travel Range, Optical Limit Switches

## L-509.40SD00

Precision Linear Stage, 85 mm Width, 2-Phase Stepper Motor, 102 mm (4") Travel Range, Optical Limit Switches

## Stages with direct position measurement

## L-509.14AD00

Precision Linear Stage, 85 mm Width, ActiveDrive DC Motor, 26 mm (1") Travel Range, Linear Encoder with A/B Quadrature Signal Transmission, Optical Limit Switches

## L-509.1ASD00

Precision Linear Stage, 85 mm Width, 2-Phase Stepper Motor, 26 mm (1") Travel Range, Linear Encoder with Sin/Cos Signal Transmission, Optical Limit Switches

## L-509.24AD00

Precision Linear Stage, 85 mm Width, ActiveDrive DC Motor, 52mm (2") Travel Range, Linear Encoder with A/B Quadrature Signal Transmission, Optical Limit Switches

## L-509.2ASD00

Precision Linear Stage, 85 mm Width, 2-Phase Stepper Motor, 52 mm (2") Travel Range, Linear Encoder with Sin/Cos Signal Transmission, Optical Limit Switches

## L-509.44AD00

Precision Linear Stage, 85 mm Width, ActiveDrive DC Motor, 102 mm (4") Travel Range, Linear Encoder with A/B Quadrature Signal Transmission, Optical Limit Switches

## L-509.4ASD00

Precision Linear Stage, 85 mm Width, 2-Phase Stepper Motor, 102 mm (4") Travel Range, Linear Encoder with Sin/Cos Signal Transmission, Optical Limit Switches

