# High-Performance Mid-Range Travel Linear Stages 

ILS SERIES<br><br>Rolis compliant

The ILS Series linear stage offers $50-250 \mathrm{~mm}$ travel range and combines fast, sub-micron resolution motion with highly stiff and robust package designs. Its extruded aluminum body has been optimized to avoid bending effects caused by the different thermal expansion coefficients of the aluminum body and steel rails. The special U-profile also provides stiffness to the structure while keeping the mass low.

A preloaded, backlash-free ballscrew provides rapid movements with fast step and settling times. The screw is accurately profiled to reduce heating factors to a minimum and extend the lifetime of the stage. Recirculating ball bearings slides ensure accurate linear motion and avoid ball cage migration found on linear ball bearings or crossed roller bearings.

Position measurements are read on a $4000 \mathrm{cts} / \mathrm{rev}$. encoder located directly on the screw to avoid additional screw/motor coupling errors. For more demanding precision positioning requirements, the HA versions feature an integrated linear scale providing $0.1 \mu \mathrm{~m}$ resolution feedback.

An upper rigid cover prevents damage to the drive train. ILS Series stages also feature a center mounted origin for repeatable initialization, limit switches to prevent over travel, and elastomeric end-of-run dampers for smooth emergency braking.

For optimal performance, we recommend the use of our motion controllers.

The ILS Series stages are supplied with a 3-meter cable for connection to our motion controllers

## ILS SERIES

SPECIFICATIONS


1) ILS-CCL used with the SMC100CC controller only.
${ }^{2)}$ Shown are peak to peak, guaranteed specifications or $\pm$ half the value as sometimes shown. For the definition of typical specifications which are about $2 X$ better than the guaranteed values, visit www.newport.com for the Motion Control Metrology Primer.
${ }^{3)}$ To obtain arcsec units, divide $\mu$ rad value by 4.8 .

## LOAD CHARACTERISTICS AND STIFFNESS



| Cz, Normal center load capacity on bearings | 250 N |
| :--- | :---: |
| $+C x /-C x$, Direct/Inverse load capacity on X axis | $<40 \mathrm{~N}$ |
| k $\alpha x$, Compliance in roll | $15 \mu \mathrm{rad} / \mathrm{Nm}$ |
| kay, Compliance in pitch | $10 \mu \mathrm{rad} / \mathrm{Nm}$ |
| k $\alpha z$, Compliance in yaw | $10 \mu \mathrm{rad} / \mathrm{Nm}$ |
| Q, Off-center load | $0 \leq \mathrm{Cz} \div(1+\mathrm{D} / 60)$ |
| with D $=$ Cantilever distance in mm |  |

## RECOMMENDED CONTROLLER/DRIVERS

| ESP301-1G | ESP301 Motor Controller/Driver, 1-Axis, GPIB, USB, RS232 |
| :--- | :--- |
| SMC100CC | Single-axis DC motor controller/driver |
| SMC100PP | Single-axis stepper motor controller/driver |
| XPS-02 | 2-axis Universal Controller/Driver, ethernet |
| XPS-RL2 | 2-axis Universal Controller/Driver, ethernet, Basic GPIO and PCO |

HIGH-PERFORMANCEMID-RANGETRAVELLINEAR STAGES

DIMENSIONS


| MODEL (METRIC) | n1 | n2 | C | TRAVEL | L |
| :--- | :---: | :---: | :---: | :---: | :---: |
| (M-)ILS100LM | 2 | 2 | $1.08(27.5)$ | $3.94(100)$ | $11.22(285)$ |
| (M-)ILS200LM | 4 | 4 | $2.76(70)$ | $7.87(200)$ | $15.16(385)$ |
| (M-)ILS300LM | 4 | 4 | $3.54(90)$ | $11.8(300)$ | $19.09(485)$ |

## Top Plate Interfaces



ORDERING INFORMATION

| Model | Series | Travel <br> $(\mathbf{m m})$ |
| :--- | :---: | :--- |
| M- Drive |  |  |

M-: $\quad$ For metric version

CC: DC motor
CCL: DC motor for SMC100CC controller
HA: DC motor with linear encoder
PP: Stepper motor


Two IMS stages, one ILS stage, and one E0120 bracket in an XYZ configuration.

## ACCESSORY: EQ120 BRACKET



An RVS80 mounted in a vertical configuration with an E0120 bracket to an ILS stage.

## ( ${ }^{\text {Newport }}{ }^{\circ}$

