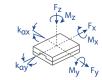
Load, max	F _X [N]	F _y [N]	F _Z [N]	M _X [N·m]	M _y [N·m]	M _Z [N·m]	k _{αχ} [μrad/N·m]	k _{αy} [μrad/N·m]
SM-001	15	15	20	0.75	4	4	80	80
								F _Z



operation in vacuum (10 ⁻⁶) are available. The PG-50 is compatible with the MMC-200 controller.
KEY FEATURES
■ Smooth, continuous ± 5° motion
■ Load capacity up to 2 kg

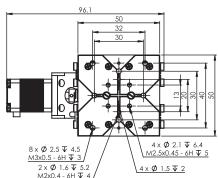
The PG-50 gonio stage performs best in limited space applications due to its compact design. High stiffness motion is achieved through pre-loaded crossed-roller bearings and a precision worm drive. These stages may be mounted in an orthogonal, space-saving arrangement to achieve pitch and roll adjustment. Versions capable of

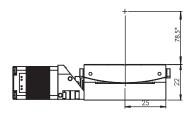
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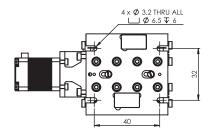
Steel crossed roller bearings ■ Low profile, 22 mm height Vacuum versions available

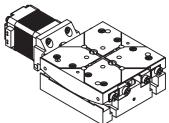
Travel range about center of rotation $[\circ]$	± 5						
Rotational Center Accuracy [mm]	< 0.1						
Wobble (Bearings) [µrad]	± 1	20					
Weight [g]	70						
Motor option	Stepper Motor (2 phase)						
Speed, max [º/s]	5						
Encoder option	None (open loop)	Analog (1 Vpp)					
Resolution, typical [º]	0.001	0.001					
Repeatability, bi-directional [°]	± 0.01	± 0.002					
Repeatability, uni-directional[º]	0.01	0.002					
Accuracy [º]	-	-					
Materials	aluminum body, steel bearing (other materials i.e. stainless steel, titanium, etc. available upon reques						

NG INFORMA	TION PG-50-	2	⊥ -	Ц,	
DRIVE	Stepper Motor, SM-001	2			
TRAVEL	± 5°	1 —			
ENCODER	None	0 —			
	Analog (1 Vpp)	2			
LIMIT SWITCH	None	0 —			
	Magnetic	1			
ENVIRONMENT	Atmospheric	o —			
	High Vacuum, 10 ⁻⁶ mbar				









- * all dimensions are in millimeters
- # Available with other center radii



Specifications are subject to change without notice