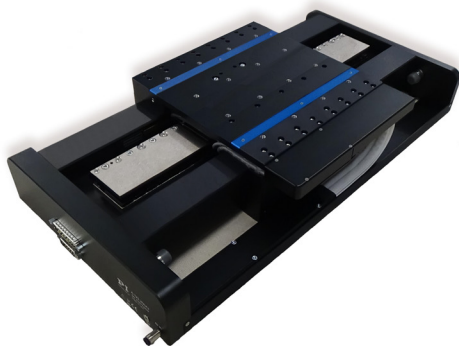


# PIglide AT3 Linear Stage with Air Bearings

## High Performance Nanopositioning Stage



### A-123

- Ideal for scanning applications or high-precision positioning
- Cleanroom compatible
- Size of the motion platform 210 mm × 210 mm
- Travel ranges 50 mm to 750 mm
- Resolution to 1 nm

### Product Overview

The stages in the PIglide are equipped with a servo drive linear motor with preloaded air bearings and integrated linear encoder. The combination of these noncontact components results in a frictionless motion platform that offers the highest performance, quality, and lifetime.

A high-force linear motor can drive the stage to top speed within a few milliseconds, and the high-capacity bearings can support payloads up to 60 kg. The laterally opposed, actively preloaded air bearing design in this model allows mounting in any orientation.

### Accessories and options

- Encoder
- PIglide filter and air preparation kits
- Single and multi-axis motion controller
- XY setups and individual configurations
- Cable track variations
- Options with counterweight for vertical (Z) orientation
- Customizations available
- Base plates made of granite and systems for reducing vibration

### Application fields

PIglide positioning systems are ideally suited for many high-precision applications such as metrology, photonics, and precision scanning in semiconductor or flat panel display manufacturing.

Thanks to the friction-free motion, no particles are formed, which makes PIglide stages ideal for cleanroom applications.

## Specifications

| Motion  | A-123.050 | A-123.100 | A-123.150 | A-123.200 | A-123.350 | A-123.500 | A-123.750 | Unit             | Tolerance |
|---|-----------|-----------|-----------|-----------|-----------|-----------|-----------|------------------|-----------|
| Active axes   | X         | X         | X         | X         | X         | X         | X         |                  |           |
| Travel range  | 50        | 100       | 150       | 200       | 350       | 500       | 750       | mm               |           |
| Pitch / yaw <sup>(1)</sup>                                    | 5         | 10        | 15        | 15        | 20        | 25        | 35        | μrad             | max.      |
| Straightness / flatness <sup>(1)</sup>                        | ±0.5      | ±0.5      | ±0.5      | ±1        | ±1.5      | ±1.5      | ±2.5      | μm               | max.      |
| Straightness / flatness per 25 mm travel range <sup>(1)</sup> | 0.1       | 0.1       | 0.1       | 0.1       | 0.1       | 0.1       | 0.1       | μm               | max.      |
| Velocity, unloaded <sup>(2)</sup>                             | 1         | 1         | 1         | 1         | 1         | 1         | 1         | m/s              | max.      |
| Acceleration, unloaded <sup>(2)</sup>                         | 30        | 30        | 30        | 30        | 30        | 30        | 30        | m/s <sup>2</sup> | max.      |

| Mechanical properties             | A-123.050   | A-123.100   | A-123.150   | A-123.200   | A-123.350   | A-123.500   | A-123.750   | Unit | Tolerance |
|-----------------------------------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|------|-----------|
| Load capacity in z <sup>(3)</sup> | 590         | 590         | 590         | 590         | 590         | 590         | 590         | N    | max.      |
| Load capacity in y <sup>(3)</sup> | 295         | 295         | 295         | 295         | 295         | 295         | 295         | N    | max.      |
| Moved mass                        | 5           | 5           | 5           | 5           | 5           | 5           | 5           | kg   |           |
| Overall mass                      | 14          | 15.5        | 16.5        | 18          | 21.5        | 25          | 32          | kg   |           |
| Guide type                        | Air bearing | Air bearing | Air bearing | Air bearing | Air bearing | Air bearing | Air bearing |      |           |

| Drive properties                        | A-123                           | Unit  | Tolerance |
|---|---------------------------------|-------|-----------|
| Drive type                              | Linear motor, ironless, 3-phase |       |           |
| Intermediate circuit voltage, effective | 48, nominal<br>80, max.         | V DC  |           |
| Peak force                              | 298                             | N     | typ.      |
| Nominal force                           | 87.5                            | N     | typ.      |
| Force constant, effective               | 19.9                            | N/A   | typ.      |
| Resistance phase-phase                  | 3.6                             | Ω     | typ.      |
| Inductivity phase-phase                 | 1.2                             | mH    | typ.      |
| Back EMF phase-phase                    | 16                              | V·s/m | max.      |
| Cabling                                 | External, moving cable          |       |           |

| Positioning                 | A-123.xxxA   | A-123.xxxB   | A-123.xxxC   |
|-----------------------------|--|--|--|
| Integrated Sensor           | Incremental linear encoder   | Absolute encoder   | Incremental linear encoder   |
| Sensor signal               | Sin/cos, 1 V peak-peak,<br>20 μm signal period   | BiSS-C   | A/B quadrature, TTL  |
| Sensor resolution           | 1.2 nm <sup>(4)</sup>  | 1 nm   | 50 nm  |
| Bidirectional repeatability | A-123.050: ± 0.25 μm <sup>(4)</sup><br>A-123.100: ± 0.25 μm <sup>(4)</sup><br>A-123.150: ± 0.25 μm <sup>(4)</sup><br>A-123.200: ± 0.25 μm <sup>(4)</sup><br>A-123.350: ± 0.5 μm <sup>(4)</sup><br>A-123.500: ± 0.5 μm <sup>(4)</sup> | A-123.050: ± 0.25 μm<br>A-123.100: ± 0.25 μm<br>A-123.150: ± 0.25 μm<br>A-123.200: ± 0.25 μm<br>A-123.350: ± 0.5 μm<br>A-123.500: ± 0.5 μm<br>A-123.750: ± 0.75 μm | A-123.050: ± 0.25 μm<br>A-123.100: ± 0.25 μm<br>A-123.150: ± 0.25 μm<br>A-123.200: ± 0.25 μm<br>A-123.350: ± 0.5 μm<br>A-123.500: ± 0.5 μm<br>A-123.750: ± 0.75 μm |

|  |   |   |   |
|--|---|---|---|
|  | A-123.750: ± 0.75 µm <sup>(4)</sup>   |   |   |
| Accuracy, uncompensated <sup>(5)</sup>           | A-123.050: ± 1 µm<br>A-123.100: ± 1 µm<br>A-123.150: ± 1.5 µm<br>A-123.200: ± 2 µm<br>A-123.350: ± 3 µm<br>A-123.500: ± 3.5 µm<br>A-123.750: ± 5 µm       | A-123.050: ± 1.5 µm<br>A-123.100: ± 1.5 µm<br>A-123.150: ± 1.5 µm<br>A-123.200: ± 1.5 µm<br>A-123.350: ± 1.5 µm<br>A-123.500: ± 1.5 µm<br>A-123.750: ± 1.5 µm | A-123.050: ± 1 µm<br>A-123.100: ± 1 µm<br>A-123.150: ± 1.5 µm<br>A-123.200: ± 2 µm<br>A-123.350: ± 3 µm<br>A-123.500: ± 3.5 µm<br>A-123.750: ± 5 µm       |
| Accuracy, with error compensation <sup>(5)</sup> | A-123.050: ± 0.5 µm<br>A-123.100: ± 0.5 µm<br>A-123.150: ± 0.5 µm<br>A-123.200: ± 0.5 µm<br>A-123.350: ± 1 µm<br>A-123.500: ± 1 µm<br>A-123.750: ± 1.5 µm | A-123.050: ± 1.5 µm<br>A-123.100: ± 1.5 µm<br>A-123.150: ± 1.5 µm<br>A-123.200: ± 1.5 µm<br>A-123.350: ± 1.5 µm<br>A-123.500: ± 1.5 µm<br>A-123.750: ± 1.5 µm | A-123.050: ± 0.5 µm<br>A-123.100: ± 0.5 µm<br>A-123.150: ± 0.5 µm<br>A-123.200: ± 0.5 µm<br>A-123.350: ± 1 µm<br>A-123.500: ± 1 µm<br>A-123.750: ± 1.5 µm |
| <b>Miscellaneous</b>                             | <b>A-123</b>  |   |   |
| Operating pressure <sup>(6)</sup>                | 75 to 85 psi (515 to 585 kPa)   |   |   |
| Air consumption                                  | < 1.0 SCFM (28 SLPM)  |   |   |
| Air quality                                      | Clean (filtered to 1.0 µm or better) - ISO 8573-1 Class 1<br>Oil free - ISO 8573-1 Class 1<br>Dry (-15 °C dew point) - ISO 8573-1 Class 3                 |   |   |
| Materials  | Hardcoat aluminum, stainless steel fasteners  |   |   |

<sup>(1)</sup> Dependent on the flatness of the surface, on which the stage is mounted.

<sup>(2)</sup> Can be limited by the payload, controller or drive.

<sup>(3)</sup> Assumes payload CG is centered no more than 50 mm above the motion platform.

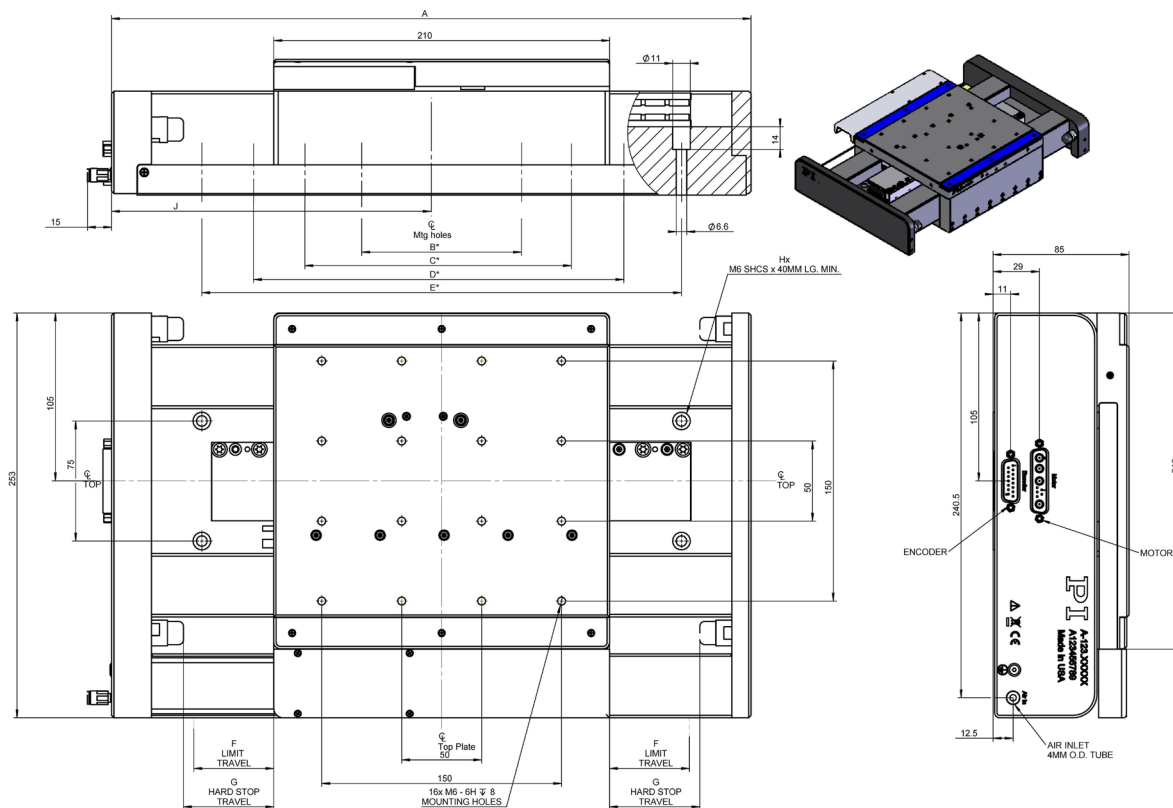
<sup>(4)</sup> Assumes 16384x interpolation. Contact PI for the use of other factors.

<sup>(5)</sup> Improved accuracy can be obtained with controller-based error compensation. The stage must be ordered with a controller from PI to reach these values.

Accuracy values assume short-term duration and do not consider the long-term effects of thermal drift on the stage.

<sup>(6)</sup> To protect the stage against damage, it is recommended to connect an air pressure sensor to the Motion-Stop input of the controller.

## Drawings and Images



| MODEL     | A    | B*  | C*  | D*  | E*   | F   | G     | Hx | J     |
|-----------|------|-----|-----|-----|------|-----|-------|----|-------|
| A-123.050 | 350  |     |     |     | 250  | 25  | 31.5  | 4  | 181.5 |
| A-123.100 | 400  | 100 |     |     | 300  | 50  | 56.5  | 8  | 206.5 |
| A-123.150 | 450  | 100 |     |     | 350  | 75  | 81.5  | 8  | 231.5 |
| A-123.200 | 500  | 100 |     |     | 400  | 100 | 106.5 | 8  | 256.5 |
| A-123.350 | 650  | 100 | 325 |     | 550  | 175 | 181.5 | 12 | 331.5 |
| A-123.500 | 800  | 100 | 300 | 500 | 700  | 250 | 256.5 | 16 | 406.5 |
| A-123.750 | 1050 | 100 | 400 | 700 | 1000 | 375 | 381.5 | 16 | 531.5 |

A-123, dimensions in mm.

\* The mounting holes are symmetric around the center line located at "J"

## Ordering Information

### Travel range 50 mm

#### A-123.050A1

PIglide AT3 Linear Stage, Air Bearing, 50 mm Travel Range, Linear Encoder with Sin/Cos Signal Transmission, 20 µm Signal Period, 3-Phase Linear Motor, 48 V

#### A-123.050B1

PIglide AT3 Linear Stage, Air Bearing, 50 mm Travel Range, Absolute Encoder, 1 nm Sensor Resolution, 3-Phase Linear Motor, 48 V

#### A-123.050C1

PIglide AT3 Linear Stage, Air Bearing, 50 mm Travel Range, Linear Encoder with A/B Quadrature Signal Transmission, 50 nm Sensor Resolution, 3-Phase Linear Motor, 48 V

## Travel range 100 mm

### A-123.100A1

PIglide AT3 Linear Stage, Air Bearing, 100 mm Travel Range, Linear Encoder with Sin/Cos Signal Transmission, 20  $\mu$ m Signal Period, 3-Phase Linear Motor, 48 V

### A-123.100B1

PIglide AT3 Linear Stage, Air Bearing, 100 mm Travel Range, Absolute Encoder, 1 nm Sensor Resolution, 3-Phase Linear Motor, 48 V

### A-123.100C1

PIglide AT3 Linear Stage, Air Bearing, 100 mm Travel Range, Linear Encoder with A/B Quadrature Signal Transmission, 50 nm Sensor Resolution, 3-Phase Linear Motor, 48 V

## Travel range 150 mm

### A-123.150A1

PIglide AT3 Linear Stage, Air Bearing, 150 mm Travel Range, Linear Encoder with Sin/Cos Signal Transmission, 20  $\mu$ m Signal Period, 3-Phase Linear Motor, 48 V

### A-123.150B1

PIglide AT3 Linear Stage, Air Bearing, 150 mm Travel Range, Absolute Encoder, 1 nm Sensor Resolution, 3-Phase Linear Motor, 48 V

### A-123.150C1

PIglide AT3 Linear Stage, Air Bearing, 150 mm Travel Range, Linear Encoder with A/B Quadrature Signal Transmission, 50 nm Sensor Resolution, 3-Phase Linear Motor, 48 V

## Travel range 200 mm

### A-123.200A1

PIglide AT3 Linear Stage, Air Bearing, 200 mm Travel Range, Linear Encoder with Sin/Cos Signal Transmission, 20  $\mu$ m Signal Period, 3-Phase Linear Motor, 48 V

### A-123.200B1

PIglide AT3 Linear Stage, Air Bearing, 200 mm Travel Range, Absolute Encoder, 1 nm Sensor Resolution, 3-Phase Linear Motor, 48 V

### A-123.200C1

PIglide AT3 Linear Stage, Air Bearing, 200 mm Travel Range, Linear Encoder with A/B Quadrature Signal Transmission, 50 nm Sensor Resolution, 3-Phase Linear Motor, 48 V

## Travel range 350 mm

### A-123.350A1

PIglide AT3 Linear Stage, Air Bearing, 350 mm Travel Range, Linear Encoder with Sin/Cos Signal Transmission, 20  $\mu$ m Signal Period, 3-Phase Linear Motor, 48 V

### A-123.350B1

PIglide AT3 Linear Stage, Air Bearing, 350 mm Travel Range, Absolute Encoder, 1 nm Sensor Resolution, 3-Phase Linear Motor, 48 V

### A-123.350C1

PIglide AT3 Linear Stage, Air Bearing, 350 mm Travel Range, Linear Encoder with A/B Quadrature Signal Transmission, 50 nm Sensor Resolution, 3-Phase Linear Motor, 48 V

## Travel range 500 mm

### A-123.500A1

PIglide AT3 Linear Stage, Air Bearing, 500 mm Travel Range, Linear Encoder with Sin/Cos Signal Transmission, 20  $\mu$ m Signal Period, 3-Phase Linear Motor, 48 V

### A-123.500B1

PIglide AT3 Linear Stage, Air Bearing, 500 mm Travel Range, Absolute Encoder, 1 nm Sensor Resolution, 3-Phase Linear Motor, 48 V

## **A-123.500C1**

PIglide AT3 Linear Stage, Air Bearing, 500 mm Travel Range, Linear Encoder with A/B Quadrature Signal Transmission, 50 nm Sensor Resolution, 3-Phase Linear Motor, 48 V

## **Travel range 750 mm**

## **A-123.750A1**

PIglide AT3 Linear Stage, Air Bearing, 750 mm Travel Range, Linear Encoder with Sin/Cos Signal Transmission, 20  $\mu$ m Signal Period, 3-Phase Linear Motor, 48 V

## **A-123.750B1**

PIglide AT3 Linear Stage, Air Bearing, 750 mm Travel Range, Absolute Encoder, 1 nm Sensor Resolution, 3-Phase Linear Motor, 48 V

## **A-123.750C1**

PIglide AT3 Linear Stage, Air Bearing, 750 mm Travel Range, Linear Encoder with A/B Quadrature Signal Transmission, 50 nm Sensor Resolution, 3-Phase Linear Motor, 48 V