Motorized Stage

CAVE-X POSITIONER XY-axis Linear Ball Guide: KYL06200/KYL06300

KYL06300-C

RoHS





Model Selection code Option code .06 20 1 5 6

e (b)

1 Travel length 200 200mm

300 300mm 2 Cover type

Uncovered

Covered

Lead 2mm

3 Ball screw lead selection

Uncovered

Covered

Uncovered

Covered Full/Half

Microstep

Ν

С

2

Model

Mechanical specification

Accuracy specification

Sensor

Single axis accuracy specification

*

Travel length

Feed screw (Ball screw)

Main materials-Finishing

Table size

Guide

Weight

Resolution (Pulse)

MAX speed

Load capacity

Origin sensor

Lost motion

Straightness

Pitching/Yawing

Backlash

Perpendicularity Limit sensor

Slit origin sensor

Provided screw (Hexagon-headed bolt)

Uni-directional positioning accuracy

Repeatability positioning accuracy

4 Motor option

- motor option			
Code	Specification		
F	High-torque		
G	High resolution		
MA	With electromagnetic brake (Driver set)		
PA	a Step (Driver set)		
U	Servo motor (Amplifier set)		
* Code N	$MA \cdot PA \cdot U$ is the set of driver and cable.		

* See page 오 P.1-077~ for details of motor option.

5 Origin sensor option

KYL06200-N2-F

KYL06200-C2-F

200mm

4.84kg

4.96kg

Within 100µm/Full stroke

12 of M4-14

Within $15\mu m$

Within 30"/Within 20"

Code	Specification
Blank	None
1	CCW right side
2	CCW left side
3	Center right side
4	Center left side
5	CW right side
6	CW left side
See pag	ge 🜔 P.1-079~ for details of or
Positi	on of origin sensor option (

ase choose one position)

SPEC

sensor option.

60×60mm

 φ 8 lead 2

Linear ball guide

Stainless-Opposite side of the end face finishing

4µm/2µm

0.2µm (1/20 on resolution)

45mm/sec

10kgf [98N]

Installed

Within $\pm 0.5 \mu$ m

Within 1µm

Within 1μ m

Within 7μ m



Cable P.1-207~
Electrical specification P.1-077~

6 Cable option

Code	Specification	Cable type
Α	2m	D214-2-2E
В	2m One end loose	D214-2-2EK
С	4m	D214-2-4E
D	4m One end loose	D214-2-4EK
E	Only connector (Cable is not included)	-
F	Robot cable 2m	D214-2-2R
G	Robot cable 2m one end loose	D214-2-2RK
Н	Robot cable 4m	D214-2-4R
J	Robot cable 4m one end loose	D214-2-4RK
М	Cable for electromagnetic brake	
Р	Cable for α step	-
U	Cable for servo motor	
Blank	Cable is not included (Standard)	-

* One end loose position to only stage opposite side.

* The price includes M, P and U. Not available non-cable.

* See page P.1-207,209~ for details of cable. * Please select "Code A, C, F or H" when connect with

stepping motor controller(DS102/112).

[Note] Please check available cable from compatibility list. Not included cable for a main body. Please choose the code as

Motor/ cable products list	Motor code	Cable code
	F,G	Blank, A~H,J
		Μ
	PA	Р
	U	U

KYL06300-N2-F

KYL06300-C2-F

300mm

6.04kg

6.24kg

Within 150µm/Full stroke

16 of M4-14

Within $25\mu m$

Within 35"/Within 20'

*Attachable in origin sensor option

Linear Ball

Motorized Stage

Χ

XY

Ζ

Horizontal

Goniomete

Rotary

Unit

Controller

XYZ

CAVE-X Linear ball

Cross Roller

Slide Guide

φ40 φ50 φ60 φ70 φ80 φ100

φ120 Other

Might be changed specification due to motors. See page > P.1-213~ for details.

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