CAVE-X POSITIONER

XY-axis Linear Ball Guide: KYG06020/KYG06030

KYG06020





RoHS

XY

Horizontal Z

XYZ

Rotary

Controller

Linear

CAVE-X Linear ball

Cross Roller

Slide Guide

φ50

φ60 φ70

φ100 φ120

Other

Option code KYG06 020-2 3

1 Travel length

20mm

30mm

020

030

Code	Specification		
С	Standard		
F	High-torque		
G	High resolution		
MA	With brake (Driver set)		
ΡΔ	a Sten (Driver set)		

2 Motor option

* See page > P.1-051~ for details of Motor option.

3 Cable option

Code	Specification	Cable type
Α	2m	D214-2-2E
В	2m One end loose	D214-2-2EK
С	4m	D214-2-4E
D	4m One end loose	D214-2-4EK
Е	Only connector (Cable is not included)	_
F	Robot cable 2m	D214-2-2R
G	Robot cable 2m one end loose	D214-2-2RK
Н	Robot cable 4m	D214-2-4R
J	Robot cable 4m one end loose	D214-2-4RK
M	Cable for brake	
Р	Cable for α step	
Blank	Cable is not included (Standard)	_

Cable P.1-207 \sim Electrical specification P.1-051 \sim

* The price includes M, P and U. Not available non-cable.

See page ◆ P.1-207,209~ for details of cable.

Please select "Code A, C, F or H" when connect with stepping motor controller(DS102/112).

[Note] Please check available cable from compatibility list. Not included cable for a main body. Please choose the code as below.

	Motor code	Cable code
Motor/cable		Blank, A∼H,J
products list	MA	M
	ΡΔ	Р

	SPEC							
Model		KYG06020-C	KYG06020-F	KYG06020-G	KYG06030-C	KYG06030-F	KYG06030-G	
Mechanical specification	Travel length		20mm				30mm	
	Table size		60×60mm		60×70mm			
<u>ड</u> .	Feed screw (Ball screw)		φ8 lead 1					
spec	Guide		Linear ball guide					
ifica	Main materials-Finishing		Stainless—Opposite side of the end face finishing					
	Weight		1.56kg	1.74kg	1.56kg	1.8kg	1.98kg	1.8kg
Acı		Full/Half	2μm,	/1μm	1μm/0.5μm	2μm/1μm		1μm/0.5μm
iii	Resolution (Pulse)	Microstep	0.1µm (1/20	on resolution)	$0.05\mu m$ (1/20 on resolution)	0.1µm (1/20	0.1 µm (1/20 on resolution)	
Accuracy specification	MAX speed		20mm/sec	30mm/sec	20mm/sec	20mm/sec	30mm/sec	20mm/sec
peci.	Load capacity		4kgf [39.2N]					
fica	Perpendicularity		Within 10 μ m/Full stroke		ке	Within 15µm/Full stroke		
tion	Pitching/Yawing		Within 20"/15"					
လ	Limit sensor		Installed					
Limit sensor Installed Origin sensor Installed								
<u> </u>	Slit origin sensor							
Provided screw (Hexagon-headed bolt) 4 of M4—14					4—14			
			×					
Single	Uni-directional pos	sitioning accuracy	Within 5µm					
20S 20	Repeatability posit	ioning accuracy	Within $\pm 0.5 \mu$ m					
Single axis accuracy specification	Lost motion		Within 1 μ m					
specifi	Backlash		Within 1μm					
afion	Straightness		Within 3μm					